

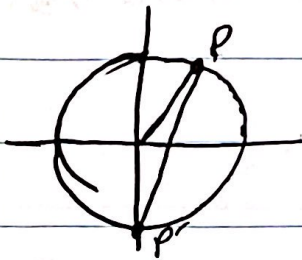
۱۲ روزه

منتها برای

①

$$\frac{a \sin(\frac{\pi}{4}) + b \cos(\frac{\pi}{4})}{a \sin(\frac{11\pi}{4}) + b \cos(\frac{11\pi}{4})} = \tan \frac{\pi}{4} \Rightarrow \frac{-\frac{\sqrt{2}}{2}a - \frac{\sqrt{2}}{2}b}{-\frac{1}{2}a + \frac{1}{2}b} = -\frac{\sqrt{2}}{1} \Rightarrow \frac{a+b}{b-a} = -\sqrt{2}$$

$$\Rightarrow \frac{a+b}{b-a} = -\sqrt{2} \Rightarrow 2a+2b = b-a \Rightarrow 3a = -b \Rightarrow \frac{b}{a} = -3$$



$$\cos \alpha = \frac{1}{\sqrt{2}} \Rightarrow 0 < \alpha < 90^\circ \Rightarrow \alpha = 45^\circ \Rightarrow \alpha + 110^\circ = 155^\circ \Rightarrow P'(\cos 155^\circ, \sin 155^\circ)$$

$$\Rightarrow \sin \alpha = \sin 45^\circ = \frac{\sqrt{2}}{2} \Rightarrow P'(\frac{1}{\sqrt{2}}, \frac{\sqrt{2}}{2})$$

$$PP' = \sqrt{(x_P - x_{P'})^2 + (y_P - y_{P'})^2} = \sqrt{(\frac{1}{\sqrt{2}} - 0)^2 + (\frac{\sqrt{2}}{2} - (-1))^2}$$

$$= \sqrt{\frac{1}{2} + (\frac{\sqrt{2}}{2} + 1)^2} = \sqrt{\frac{1}{2} + \frac{2}{2} + \sqrt{2} + 1} = \sqrt{\frac{1}{2} + \frac{3}{2} + \sqrt{2}} = \sqrt{2 + \sqrt{2}}$$

$$\Rightarrow PP' = \frac{1 + \sqrt{2}}{\sqrt{2}} = \frac{\sqrt{2} + 2}{2} \Rightarrow \text{طول } PP' = (1 + \sqrt{2}) \cdot \frac{1}{\sqrt{2}} = \frac{2 + \sqrt{2}}{2}$$

$$\frac{\pi}{9} = \frac{\text{Degree}}{180} \Rightarrow \text{Deg} = 20^\circ$$

③ ابتدا از مکان رابره درجه تبدیل می‌کیر

در دایره در ساعت 4:M، عقربه ساعت‌شمار $\frac{M}{60}$ درجه از 12 حرکت کرده است. (در هر دایره دقیقه عقربه ساعت‌شمار)

$$\frac{M}{60} = 20^\circ \Rightarrow M = 120' \Rightarrow \text{ساعت: 4:20}$$

تفاوت این ساعت 4:M' دایره:

$$\alpha = \left| \frac{11}{2}M - 30H \right| \Rightarrow 20^\circ = \left| \frac{11}{2}M - 30(3) \right| = \left| \frac{11}{2}M - 90 \right|$$

عقربه ساعت‌شمار

$$\Rightarrow \left\{ \begin{array}{l} 20^\circ = \frac{11}{2}M - 90 \Rightarrow \frac{11}{2}M = 110 \Rightarrow M = 20' \\ 20^\circ = 90 - \frac{11}{2}M \Rightarrow \frac{11}{2}M = 70 \Rightarrow M = \frac{140}{11} = 12 \frac{8}{11} \end{array} \right.$$

$$\Rightarrow \left\{ \begin{array}{l} \text{بار دوم} \\ \text{بار اول} \end{array} \right.$$



$$\Rightarrow \frac{-\pi}{2} < \alpha < \frac{\pi}{2} \Rightarrow -1 < \sin \alpha < 1 \Rightarrow -\frac{1}{\gamma} < \frac{m-\gamma}{\omega} < 1 \Rightarrow -\frac{\omega}{\gamma} < m - \gamma \frac{\omega}{\gamma} \quad (5)$$

$$\Rightarrow \frac{1}{\gamma} < m < 1 \rightarrow m = \{1, 2, 3, 4, 5, 6, 7, 8\} \rightarrow \boxed{\text{مستقیم}}$$

$$\tan 10^\circ = \frac{1}{f} \Rightarrow \frac{\sin 10^\circ}{\cos 10^\circ} = \frac{1}{f} \Rightarrow \cos 10^\circ = f \sin 10^\circ \quad (7)$$

$$= \frac{\sin(90^\circ + 10^\circ) + k \cos(90^\circ - 10^\circ)}{\cos(110^\circ - 10^\circ) + \gamma \sin(110^\circ + 10^\circ)} = \frac{\cos 10^\circ - k \sin 10^\circ}{-\cos 10^\circ - \gamma \sin 10^\circ} = \frac{f \sin 10^\circ - k \sin 10^\circ}{-f \sin 10^\circ - \gamma \sin 10^\circ}$$

$$= \frac{(f-k) \sin 10^\circ}{-\gamma \sin 10^\circ} = \frac{k-f}{\gamma} = \gamma \Rightarrow k-f = \gamma \Rightarrow k = \gamma \gamma \quad (8)$$

$$\frac{1 - \cos \alpha}{1 + \cos \alpha} = \gamma \Rightarrow 1 - \cos \alpha = \gamma + \gamma \cos \alpha \Rightarrow \gamma \cos \alpha = \frac{1}{\gamma} \Rightarrow \cos \alpha = \frac{1}{\gamma^2} \Rightarrow \cos \alpha = \frac{1}{9} \quad (9)$$

$$\Rightarrow \frac{1}{\cos \alpha} = 9 \Rightarrow 1 + \tan^2 \alpha = 9 \Rightarrow \tan^2 \alpha = 8 \Rightarrow \tan \alpha = \sqrt{8} \Rightarrow \cot \alpha = \frac{1}{\sqrt{8}}$$

$$\frac{\tan(\frac{\pi}{\gamma} - \alpha) - \cot(\pi - \alpha)}{\cot(\frac{\pi}{\gamma} - \alpha) + \gamma \tan(\pi - \alpha)} = \frac{\cot \alpha - (-\cot \alpha)}{\tan \alpha - \gamma \tan \alpha} = \frac{\gamma \cot \alpha}{-\tan \alpha} = -\gamma \cot \alpha = -\gamma \left(\frac{1}{\sqrt{8}}\right) = -\frac{1}{f}$$

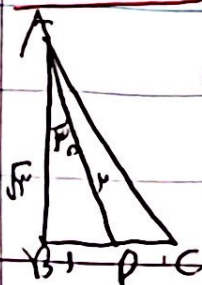
$$\frac{10^\circ}{180} = \frac{\text{Rad}}{\pi} \Rightarrow \text{Rad} = \frac{3\pi}{20}$$

$$l = R\theta$$

(1) ابتدا زاویه 10° را به رادیان تبدیل می‌کنیم

$$\begin{aligned} \text{طول کمان A} &= R_A \times \frac{3\pi}{20} \\ \text{طول کمان B} &= R_B \times \frac{9\pi}{10} \end{aligned} \Rightarrow R_A \times \frac{3\pi}{20} = R_B \times \frac{9\pi}{10} \Rightarrow \frac{R_A}{R_B} = \frac{\gamma}{f} \Rightarrow \frac{R_A^p}{R_B^p} = \frac{\gamma}{f} \Rightarrow \frac{\pi R_A^p}{\pi R_B^p} = \frac{\gamma}{f}$$

$$\Rightarrow \frac{S_A}{S_B} = \frac{\gamma}{f}$$



$$\sin 30^\circ = \frac{BD}{AD} = \frac{1}{\gamma} \Rightarrow AD = \gamma, \cos 30^\circ = \frac{AB}{AD} = \frac{\sqrt{3}}{\gamma} \Rightarrow \gamma = \frac{\sqrt{3}}{\frac{\sqrt{3}}{\gamma}} = \sqrt{3} \quad (10)$$

$$S_{ABC} = \frac{1}{2} \times \sqrt{3} \times BC = \sqrt{3} \Rightarrow BC = \gamma \Rightarrow AC^2 = (\gamma)^2 + (\sqrt{3})^2 = \gamma^2 + 3 = \gamma^2 \Rightarrow AC = \sqrt{3}$$

$$\Rightarrow \sin \hat{C} = \frac{AB}{AC} = \frac{\sqrt{3}}{\sqrt{3}} = 1, \cos \hat{C} = \frac{BC}{AC} = \frac{\gamma}{\sqrt{3}} \Rightarrow \sin \gamma \hat{C} = \gamma \sin \hat{C} \cos \hat{C}$$

$$\Rightarrow \sin \gamma \hat{C} = \gamma \left(\frac{\sqrt{3}}{\gamma}\right) \left(\frac{\gamma}{\sqrt{3}}\right) = \frac{\gamma \sqrt{3}}{\gamma} = \sqrt{3}$$

$$EH \perp AD, CD \perp AD \Rightarrow EH \parallel CD \xrightarrow{\text{قصدتالی}} \frac{EH}{ND} = \frac{AH}{AD} \Rightarrow \frac{EH}{y} = \frac{y}{y} \Rightarrow EH = \frac{y}{y}$$

(10)

$$\tan \alpha = \frac{\frac{y}{y}}{y} = \frac{y}{y}, \quad \tan(\alpha + \theta) = \frac{y}{y} \quad (\text{رابطه تانژانت})$$

$$\tan(\alpha + \theta) = \frac{\tan \alpha + \tan \theta}{1 - \tan \alpha \tan \theta} \Rightarrow \frac{\frac{y}{y} + \tan \theta}{1 - \frac{y}{y} \tan \theta} = \frac{y}{y} \Rightarrow \frac{y}{y} + \tan \theta = \frac{y}{y} - \tan \theta$$

$$\Rightarrow y \tan \theta = \frac{y}{y} - \frac{y}{y} = \frac{a}{y} \Rightarrow \tan \theta = \frac{a}{1y} \Rightarrow \cot \theta = \frac{1y}{a} \Rightarrow 1 + \cot^2 \theta = \frac{1}{\sin^2 \theta}$$

$$\Rightarrow 1 + \frac{1y^2}{Pa} = \frac{1y^2}{Pa} = \frac{1}{\sin^2 \theta} \Rightarrow \sin^2 \theta = \frac{Pa}{1y^2} \xrightarrow{\alpha \theta < 90^\circ} \sin \theta = \pm \frac{a}{1y}$$

(مربع 90°)

